Communicative rotary actuator fail-safe for adjusting dampers with safety function in technical building installations

- Air damper size up to approx. $0.5 \mathrm{~m}^{2}$
- Torque motor 2.5 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2... 10 V variable
- Position feedback 2... 10 V variable
- Conversion of sensor signals
- Communication via Belimo MP-Bus


Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | $50 / 60 \mathrm{~Hz}$ |
|  | Nominal voltage range | AC 19.2...28.8 V / DC 21.6...28.8 V |
|  | Power consumption in operation | 2.5 W |
|  | Power consumption in rest position | 1 W |
|  | Power consumption for wire sizing | 4 VA |
|  | Connection supply / control | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |
|  | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | 2.5 Nm |
|  | Torque fail-safe | 2.5 Nm |
|  | Operating range Y | 2... 10 V |
|  | Input Impedance | $100 \mathrm{k} \Omega$ |
|  | Options positioning signal | Open/close |
|  | Operating range Y variable | Start point 0.5... 30 V <br> End point 2.5... 32 V |
|  | Position feedback U | 2... 10 V |
|  | Position feedback U note | Max. 0.5 mA |
|  | Position feedback U variable | Start point 0.5... 8 V End point 2.5. 10 V |
|  | Position accuracy | $\pm 5 \%$ |
|  | Direction of motion motor | selectable with switch L/R |
|  | Direction of motion note | $\mathrm{Y}=0 \mathrm{~V}$ : At switch position 0 (ccw rotation) / 1 (cw rotation) |
|  | Direction of motion variable | electronically reversible |
|  | Direction of motion fail-safe | selectable by mounting L/R |
|  | Manual override | No |
|  | Angle of rotation | Max. $95^{\circ}$ |
|  | Angle of rotation note | adjustable starting at $37 \%$ in $2.5 \%$ steps (with mechanical end stop) |
|  | Running time motor | $150 \mathrm{~s} / 90^{\circ}$ |
|  | Running time fail-safe | $<25 \mathrm{~s} / 90^{\circ}$ |
|  | Adaptation setting range | manual |
|  | Adaptation setting range variable | No action |
|  |  | Adaptation when switched on |
|  |  | Adaptation after using the rotation switch |
|  | Override control | $\begin{aligned} & \text { MAX (maximum position) }=100 \% \\ & \text { MIN (minimum position) }=0 \% \\ & \text { ZS (intermediate position, AC only })=50 \% \end{aligned}$ |
|  | Override control variable | $\begin{aligned} & \text { MAX }=(\text { MIN }+32 \%) . . .100 \% \\ & \text { MIN }=0 \% \ldots(\text { MAX }-32 \%) \\ & Z S=\text { MIN...MAX } \end{aligned}$ |
|  | Sound power level, motor | 50 dB (A) |
|  | Mechanical interface | Universal shaft clamp 6...12.7 mm |
|  | Position indication | Mechanical |
|  | Service life | Min. 60'000 fail-safe positions |
| Safety | Protection class IEC/EN | III Safety Extra-Low Voltage (SELV) |
|  | Degree of protection IEC/EN | IP42 |
|  | EMC | CE according to 2014/30/EU |
|  | Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |

## Safety notes



- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.


## Product features

## Mode of operation

The actuator moves the damper to the operating position at the same time as tensioning the return spring. The damper is turned back to the fail-safe position by spring force when the supply voltage is interrupted.
Conventional operation:
The actuator is connected with a standard modulating signal of $0 . . .10 \mathrm{~V}$ and drives to the position defined by the positioning signal. Measuring voltage $U$ serves for the electrical display of the damper position $0.5 \ldots 100 \%$ and as slave control signal for other actuators.
Operation on Bus:
The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection $U$ serves as communication interface and does not supply an analogue measuring voltage.
Converter for sensors Connection option for a sensor (active sensor or switching contact). The MFT actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.
Parametrisable actuators The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.
Simple direct mounting Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.
Adjustable angle of rotation
Adjustable angle of rotation with mechanical end stops.
High functional reliability
The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0\%).
The actuator then moves into the position defined by the positioning signal.


## Adaption and synchronisation

An adaption can be triggered manually by switching the direction of rotation switch from the left to the right twice within 5s or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after actuating the direction of rotation switch once is programmed. The synchronisation is in the home position ( $0 \%$ ).
The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

## Accessories

| Gateways | Description | Type |
| :---: | :---: | :---: |
|  | Gateway MP to Modbus RTU | UK24MOD |
|  | Gateway MP zu BACnet MS/TP | UK24BAC |
|  | Gateway MP to LonWorks | UK24LON |
|  | Gateway MP to KNX | UK24EIB |
|  | Description | Type |
| Electrical accessories | Signal converter voltage/current $100 \mathrm{k} \Omega$ Supply AC/DC 24 V | Z-UIC |
|  | Range controller for wall mounting | SBG24 |
|  | Positioner for wall mounting | SGA24 |
|  | Positioner for built-in mounting | SGE24 |
|  | Positioner for front-panel mounting | SGF24 |
|  | Positioner for wall mounting | CRP24-B1 |
|  | Description | Type |
| Mechanical accessories | Actuator arm | AH-TF |
|  | Shaft extension 170 mm Ø10 mm for damper shaft Ø $6 \ldots 16 \mathrm{~mm}$ | AV6-20 |
|  | Ball joint suitable for damper crank arm KH8 / KH10 | KG10A |
|  | Ball joint suitable for damper crank arm KH8 | KG8 |
|  | Damper crank arm Slot width 8.2 mm , clamping range $\varnothing 10 \ldots 18 \mathrm{~mm}$ | KH8 |
|  | Screw fastening kit | SB-TF |
|  | Angle of rotation limiter, with end stop | ZDB-TF |
|  | Form fit adapter $8 \times 8 \mathrm{~mm}$ | ZF8-TF |
|  | Mounting kit for linkage operation for flat and side installation | ZG-TF1 |
|  | Anti-rotation mechanism 180 mm , Multipack 20 pcs. | Z-ARS180 |
|  | Description | Type |
| Service Tools | Service Tool, with ZIP-USB function | ZTH EU |
|  | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |
|  | Adapter for Service-Tool ZTH | MFT-C |

## Electrical installation

Notes $\quad$ - Connection via safety isolating transformer.

## Electrical installation

## Wiring diagrams

AC/DC 24 V , modulating


Cable colours:
1 = black
2 = red
3 = white
5 = orange

Operation on the MP-Bus


## Cable colours:

1 = black
2 = red
3 = white
5 = orange

## Functions

Functions when operated on MP-Bus

Connection on the MP-Bus


Connection of active sensors

A) more actuators and sensors (max.8)

MP-Bus Network topology


There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable - no shielding or twisting necessary - no terminating resistors required

A) more actuators and sensors (max.8)

- Switching current 16 mA @ 24 V
- Start point of the operating range must be parameterised on the MP actuator as $\geq 0.5 \mathrm{~V}$


## Functions

## Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts
Override control with AC 24 V with rotary switch



Control remotely 0... $100 \%$ with Minimum limit with positioner SG.. positioner SG..


Follow-up control (position-dependent)


## Caution:

The operating range must be set to DC $2 \ldots 10 \mathrm{~V}$.
The $500 \Omega$ resistor converts the $4 . . .20 \mathrm{~mA}$ current signal to a voltage signal DC $2 \ldots . .10 \mathrm{~V}$

Functional check


## Procedure

1. Connect 24 V to connections 1
and 2
2. Disconnect connection 3:

- with direction of rotation 0 :

Actuator rotates to the left

- with direction of rotation 1 :

Actuator rotates to the right
3. Short-circuit connections 2 and 3:

- Actuator runs in opposite direction


## Functions

Functions for devices with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts


Control open/close


Override control and limiting with AC 24 V with rotary switch


1) Caution: This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V .

Operating controls and indicators

(1) MP addressing

Move direction of rotation switch in opposite position and backwards (within 4 seconds)

## Service

Service Tools connection
The actuator can be parametrised by ZTH EU via terminal connection. For extended parametrisation the PC tool can be connected.
Connection ZTH EU / PC-Tool


## Dimensions [mm]

Spindle length

| $\triangle$ | Min. 84 |
| :---: | :---: |
| - | Min. 20 |

## Clamping range

| $\nabla \overline{\nabla I}$ | $\widehat{\nabla I}$ |
| :---: | :---: |
| $6 \ldots 12.7$ | $6 \ldots 12.7$ |

Dimensional drawings



## Further documentation

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology

