Communicative rotary actuator failsafe for adjusting dampers in technical building installations

- Air damper size up to approx. $4 \mathrm{~m}^{2}$
- Torque motor 20 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2... 10 V variable
- Position feedback 2... 10 V variable
- Conversion of sensor signals
- Communication via Belimo MP-Bus


Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | $50 / 60 \mathrm{~Hz}$ |
|  | Nominal voltage range | AC 19.2...28.8 V / DC 21.6...28.8 V |
|  | Power consumption in operation | 8.5 W |
|  | Power consumption in rest position | 3.5 W |
|  | Power consumption for wire sizing | 11 VA |
|  | Connection supply / control | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |
|  | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | 20 Nm |
|  | Torque fail-safe | 20 Nm |
|  | Communicative control | MP-Bus |
|  | Operating range Y | 2... 10 V |
|  | Input Impedance | $100 \mathrm{k} \Omega$ |
|  | Options positioning signal | Open/close |
|  |  | 3-point (AC only) |
|  |  | Modulating (DC 0... 32 V ) |
|  | Operating range Y variable | Start point 0.5... 30 V |
|  |  | End point 2.5... 32 V |
|  | Position feedback U | 2... 10 V |
|  | Position feedback U note | Max. 0.5 mA |
|  | Position feedback U variable | Start point 0.5... 8 V |
|  |  | End point 2.5... 10 V |
|  | Position accuracy | $\pm 5 \%$ |
|  | Direction of motion motor | selectable with switch L/R |
|  | Direction of motion variable | electronically reversible |
|  | Direction of motion fail-safe | selectable by mounting L/R |
|  | Manual override | by means of hand crank and locking switch |
|  | Angle of rotation | Max. $95^{\circ}$ |
|  | Angle of rotation note | adjustable starting at $33 \%$ in $2.5 \%$ steps (with mechanical end stop) |
|  | Running time motor | $150 \mathrm{~s} / 90^{\circ}$ |
|  | Running time motor variable | 70... 220 s |
|  | Running time fail-safe | $<20 \mathrm{~s} / 90^{\circ}$ |
|  | Running time fail-safe note | @ -20...50 ${ }^{\circ} \mathrm{C} /<60 \mathrm{~s} @-30^{\circ} \mathrm{C}$ |
|  | Adaptation setting range | manual |
|  | Adaptation setting range variable | No action |
|  |  | Adaptation when switched on |
|  |  | Adaptation after using the hand crank |
|  | Override control | MAX (maximum position) $=100 \%$ |
|  |  | MIN (minimum position) $=0 \%$ |
|  |  | ZS (intermediate position, AC only) $=50 \%$ |
|  | Override control variable | MAX $=(\mathrm{MIN}+32 \%) . . .100 \%$ |
|  |  | MIN $=0 \% \ldots($ MAX $-32 \%)$ |
|  |  | ZS $=$ MIN...MAX |
|  | Sound power level, motor | $40 \mathrm{~dB}(\mathrm{~A})$ |
|  | Mechanical interface | Universal shaft clamp 10...25.4 mm |
|  | Position indication | Mechanical |
|  | Service life | Min. 60'000 fail-safe positions |
| Safety | Protection class IEC/EN | III Safety Extra-Low Voltage (SELV) |

Technical data

## Safety notes



- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.
- Cables must not be removed from the device.


## Product features

| Mode of operation | Conventional operation: <br> The actuator is connected with a standard modulating signal of $0 . . .10 \mathrm{~V}$ and drives <br> to the position defined by the positioning signal. Measuring voltage U serves for the <br> electrical display of the damper position $0.5 \ldots 100 \%$ and as slave control signal for <br> other actuators. <br> Operation on Bus: <br> The actuator receives its digital positioning signal from the higher level controller via <br> the MP-Bus and drives to the position defined. Connection U serves as communication <br> interface and does not supply an analogue measuring voltage. |
| :--- | :--- |
| Converter for sensors | Connection option for a sensor (passive or active sensor or switching contact). The <br> MP actuator serves as an analogue/digital converter for the transmission of the sensor <br> signal via MP-Bus to the higher level system. |
| Simple direct mounting |  |
|  | The factory settings cover the most common applications. Single parameters can be <br> modified with the Belimo Service Tools MFT-P or ZTH EU. <br> Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with <br> an anti-rotation device to prevent the actuator from rotating. |
| Manual override | By using the hand crank the damper can be actuated manually and engaged with the <br> locking switch at any position. Unlocking is carried out manually or automatically by <br> applying the operating voltage. |
| Adjustable angle of rotation | Adjustable angle of rotation with mechanical end stops. |

High functional reliability The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0\%).
The actuator then moves into the position defined by the positioning signal.

## Adaption and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after actuating the hand crank is programmed. The synchronisation is in the home position (0\%).
The actuator then moves into the position defined by the positioning signal.
A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

| Accessories |  |  |
| :---: | :---: | :---: |
| GatewaysElectrical accessories | Description | Type |
|  | Gateway MP to Modbus RTU | UK24MOD |
|  | Gateway MP zu BACnet MS/TP | UK24BAC |
|  | Gateway MP to LonWorks | UK24LON |
|  | Gateway MP to KNX | UK24EIB |
|  | Description | Type |
|  | Auxiliary switch $2 \times$ SPDT | S2A-F |
|  | Feedback potentiometer $200 \Omega$ | P200A-F |
|  | Feedback potentiometer $1 \mathrm{k} \Omega$ | P1000A-F |
|  | Signal converter voltage/current $100 \mathrm{k} \Omega$ Supply AC/DC 24 V | Z-UIC |
|  | Range controller for wall mounting | SBG24 |
|  | Positioner for wall mounting | SGA24 |
|  | Positioner for built-in mounting | SGE24 |
|  | Positioner for front-panel mounting | SGF24 |
|  | Positioner for wall mounting | CRP24-B1 |
|  | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin service socket for Belimo device | ZK1-GEN |
|  | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal | ZK2-GEN |
|  | Connecting board MP-Bus for wiring boxes EXT-WR-FP..-MP | ZFP2-MP |
|  | MP-Bus power supply for MP actuators | ZN230-24MP |
|  | Description | Type |
| Mechanical accessories | Shaft extension 240 mm Ø20 mm for damper shaft Ø 8...22.7 mm | AV8-25 |
|  | End stop indicator | IND-AFB |
|  | Shaft clamp reversible, for central mounting, for damper shafts $\varnothing 12.7$ / 19.0 / 25.4 mm | K7-2 |
|  | Ball joint suitable for damper crank arm KH8 / KH10 | KG10A |
|  | Ball joint suitable for damper crank arm KH8 | KG8 |
|  | Damper crank arm Slot width 8.2 mm , clamping range $\varnothing 10 \ldots 18 \mathrm{~mm}$ | KH8 |
|  | Actuator arm, for $3 / 4^{\prime \prime}$ shafts, clamping range $\varnothing 10 \ldots 22 \mathrm{~mm}$, Slot width 8.2 mm | KH-AFB |
|  | Form fit insert $10 \times 10 \mathrm{~mm}$, Multipack 20 pcs . | ZF10-NSA-F |
|  | Form fit insert $12 \times 12 \mathrm{~mm}$, Multipack 20 pcs . | ZF12-NSA-F |
|  | Form fit insert $15 \times 15 \mathrm{~mm}$, Multipack 20 pcs. | ZF15-NSA-F |
|  | Form fit insert $16 \times 16 \mathrm{~mm}$, Multipack 20 pcs . | ZF16-NSA-F |
|  | Mounting kit for linkage operation for flat and side installation | ZG-AFB |
|  | Base plate extension | Z-SF |
|  | Anti-rotation mechanism 230 mm , Multipack 20 pcs. | Z-ARS230L |
|  | Hand crank 63 mm | ZKN2-B |

## Accessories

|  | Description | Type |
| :--- | :--- | :--- |
| Service Tools | Service Tool, with ZIP-USB function | ZTH EU |
|  | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |
|  | Adapter for Service-Tool ZTH | MFT-C |

## Electrical installation

Notes $\quad$ - Connection via safety isolating transformer.

## Wiring diagrams

AC/DC 24 V , modulating


## Cable colours:

1 = black
2 = red
3 = white
5 = orange
Operation on the MP-Bus


## Cable colours:

1 = black
2 = red
3 = white
5 = orange

## Functions

Functions when operated on MP-Bus

Connection on the MP-Bus

A) more actuators and sensors (max.8)

Connection of active sensors

A) more actuators and sensors (max.8)

- Supply AC/DC 24 V
- Output signal DC $0 . . .10 \mathrm{~V}$
(max. DC 0... 32 V )
- Resolution 30 mV

MP-Bus Network topology


There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).
Supply and communication in one and the same 3 -wire cable

- no shielding or twisting necessary
- no terminating resistors required

Connection of external switching contact

A) more actuators and sensors (max.8)

- Switching current $16 \mathrm{~mA} @ 24 \mathrm{~V}$
- Start point of the operating range must be parameterised on the MP actuator as $\geq 0.5 \mathrm{~V}$

Connection of passive sensors


| Ni1000 | $-28 \ldots+98^{\circ} \mathrm{C}$ | $850 \ldots 1600 \Omega^{2)}$ |
| :--- | :--- | :--- |
| PT1000 | $-35 \ldots+155^{\circ} \mathrm{C}$ | $850 \ldots 1600 \Omega^{2)}$ |
| NTC | $-10 \ldots+160^{\circ} \mathrm{C}^{1)}$ | $200 \Omega . . .60 \mathrm{k} \Omega^{2)}$ |

A) more actuators and sensors
(max.8)

1) Depending on the type
2) Resolution 1 Ohm

## Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts


Override control with AC 24 V with rotary switch


Control remotely $0 . . .100 \%$ with Minimum limit with positioner SG.. positioner SG..



Follow-up control (position-dependent)


## Caution:

The operating range must be set to DC 2... 10 V .
The $500 \Omega$ resistor converts the $4 . . .20 \mathrm{~mA}$ current signal to a voltage signal DC 2... 10 V

## Functions

Functional check


## Procedure

1. Connect 24 V to connections 1
and 2
2. Disconnect connection 3:

- with direction of rotation 0 :

Actuator rotates to the left

- with direction of rotation 1 :

Actuator rotates to the right
3. Short-circuit connections 2 and 3:

- Actuator runs in opposite direction


## Functions for devices with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts


Control open/close



Control 3-point

Override control and limiting with AC 24 V with rotary switch


1) Caution: This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V .

## Operating controls and indicators


(1) Membrane key and LED display green

Off: $\quad$ No power supply or malfuntion
On: In operation
Press button: Triggers angle of rotation adaptation, followed by standard mode
(2) Membrane key and LED display gelb

Off:
Standard mode
Flickering: MP communication active
On: Adaptation and synchronising process active
Flashing:
Request for addressing from MP master
Press button:
Confirmation of the addressing
(3) Service plug

For connecting parameterisation and service tools

## Operating elements

The manual override, locking switch and direction of rotation switch elements are available on both sidesa

## Service

Service Tools connection
The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.
Connection ZTH EU / PC-Tool


## Dimensions [mm]

Spindle length


Clamping range

|  | OI | $\square$ | $\Delta I$ |
| :---: | :---: | :---: | :---: |
|  | 10... 22 | 10 | 14...25.4 |
|  | O! |  | $\square \underline{I}$ |
|  | 19...25. |  | 12... 18 |

Dimensional drawings


Further documentation

[^0]
[^0]:    - Overview MP Cooperation Partners
    - Tool connections
    - Introduction to MP-Bus Technology

