

Technical data sheet

SF24A-MOD

BACneti dodbus MP22BUS

Communicative spring-return actuator with emergency control function for adjusting dampers in technical building installations

- Torque motor 20 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid mode
- Conversion of sensor signals
- Communication via BACnet MS/TP, Modbus RTU, Belimo-MP-Bus or conventional control



Technical data

Electrical data	Nominal voltage	AC/DC 24 V		
	Nominal voltage frequency	50/60 Hz		
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V		
	Power consumption in operation	8.5 W		
	Power consumption in rest position	3.5 W		
	Power consumption for wire sizing	11 VA		
	Connection supply / control	Cable 1 m, 6 x 0.75 mm ²		
Functional data	Nominal torque	Min. 20 Nm		
	Torque spring return	20 Nm		
	Communicative control	BACnet MS/TP		
		Modbus RTU (ex works)		
		MP-Bus		
	Operating range Y	DC 210 V		
	Operating range Y variable	DC 0.510 V		
	Position feedback U	DC 210 V		
	Position feedback U note	Max. 1 mA		
	Position feedback U variable	Start point DC 0.58 V		
		End point DC 210 V		
	Position accuracy	±5%		
	Direction of motion motor	selectable with switch L / R		
	Direction of motion emergency control function	selectable by mounting L / R		
	Manual override	by means of hand crank and locking switch		
	Angle of rotation	Max. 95°		
	Angle of rotation note	adjustable starting at 33% in 2.5% steps (with mechanical end stop)		
	Running time motor	150 s / 90°		
	Running time motor variable	70220 s		
	Running time emergency control position	<20 s / 90°		
	Running time emergency setting position note	@ -2050 °C / <60 s @ -30 °C		
	Adaption setting range	manual		
	Adaption setting range variable	No action		
		Adaption when switched on		
		Adaption after pushing the gear disengagement button		
	Override control, controllable via bus	MAX (maximum position) = 100%		
	communication	MIN (minimum position) = 0%		
		ZS (intermediate position) = 50%		
	Override control variable	MAX = (MIN + 32%)100%		
		MIN = 0%(MAX - 32%)		
	Sound nowor loval Mator	ZS = MINMAX		
	Sound power level Motor	40 dB(A)		
	Damper spindle	Universal spindle clamp 1025.4 mm		
	Position indication Service life	Mechanical		
		Min. 60,000 emergency positions		
Safety	Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)		
	Protection class UL	UL Class 2 Supply		
	Degree of protection IEC/EN	IP54		

SF24A-MOD	Spring-return actuator, modulatin communicative hybrid mode, AC/DC 24 V, 20 Nm,	DLLIVIO		
Technical data				
Safety Notes	in aircraft or in any other airborne me	•		
	 Outdoor application: only possible in case that no (sea)water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet. Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation. The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user. Cables must not be removed from the device. To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed. The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed. 			
Product features				
Mode of operation		I interface for BACnet MS/TP, Modbus RTU and ing signal from the control system and returns		
Converter for sensors		e, active or with switching contact). In this way, ily digitised and transferred to the bus systems		
Parameterisable actuators	The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU. The communication parameters of the bus systems (address, baud rate etc.) are set with the ZTH EU. Pressing the "Address" button on the actuator while connecting the supply voltage, resets the communication parameters to the factory setting. Quick addressing: The BACnet and Modbus address can alternatively be set using the buttons on the actuator and selecting 1 to 16. The value selected is address.			
Combination analogue - communicative (hybrid mode)				
Simple direct mounting	Simple direct mounting on the damper supplied with an anti-rotation device to	spindle with an universal spindle clamp, prevent the actuator from rotating.		
Manual override		an be actuated manually and engaged with the ng is carried out manually or automatically by		
Adjustable angle of rotation	Adjustable angle of rotation with mech	anical end stops.		
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.			

SF24A-MOD	Spring-return actuator, modulating communicative hybrid mode, AC/DC 24 V, 20 Nm,		
Product features			
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal.		
Adaption and synchronisation	An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after actuating the hand crank is programmed. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)		

Accessories

	Description	Туре
Electrical accessories	Auxiliary switch, 2 x SPDT	
	Feedback potentiometer, 200 Ohm, incl. installation accessories	P200A-F
	Feedback potentiometer 1 kOhm, incl. installation accessories	P1000A-F
	Connecting cable 5 m, A+B: RJ12 6/6, To ZTH EU	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4, B: Free wire end, To ZTH EU	ZK2-GEN
	Description	Туре
Mechanical accessories	Shaft extension 240 mm, for damper spindles \emptyset 825 mm or \emptyset 1025 mm	AV8-25
	End stop indicator for NFA / SFA	IND-AFB
	Spindle clamp set for NFA/SFA (1", 3/4", 1/2")	K7-2
	Straight ball joint with M8, suitable for damper crank arm KH8	KG10A
	Angled ball joint with M8, suitable for damper crank arm KH8	KG8
	Damper crank arm, for damper spindles	KH8
	Damper crank arm for NFA / SFA, for 3/4" spindles	KH-AFB
	Form fit insert 10x10 mm, for NFA / SFA	ZF10-NSA-F
	Form fit insert 12x12 mm, for NFA / SFA	ZF12-NSA-F
	Form fit insert 16x16 mm, for NFA / SFA	ZF16-NSA-F
	Damper crank arm, for spring return actuators NG	ZG-AFB
	Base plate extension for NFA / SFA	Z-SF
	Anti-rotation mechanism 230 mm	Z-ARS230L
	Hand crank 63 mm for BFL, BFN, NFA / SFA / EFA	ZKN2-B
	Description	Туре
Service Tools	Service tool for parametrisable and communicative Belimo actuators / VAV controller and HVAC performance devices	ZTH EU
	Belimo PC-Tool, software for adjustments and diagnostics	MFT-P
	Adapter to Service Tool ZTH	MFT-C

Notes Connection via safety isolating transformer. The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable RS485 regulations. Modbus / BACnet: Supply and communication are not galvanically isolated. Connect earth signal of the devices with one another.

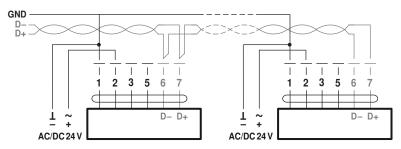
Spring-return actuator, modulating communicative hybrid mode, AC/DC 24 V, 20 Nm,



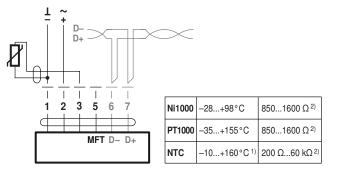
Electrical installation

Wiring diagrams

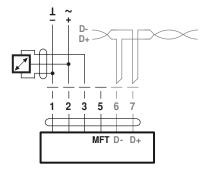
BACnet MS/TP / Modbus RTU



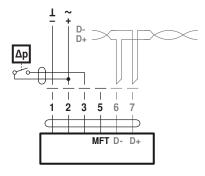
Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



Connection with active sensor, e.g. 0...10 V @ 0...50 °C



Connection with switching contact, e.g. Δp monitor



2) Resolution 1 Ohm

Possible voltage range: 0...32 V (resolution 30 mV)

1) depending on type

Requirements for switching contact: The switching contact must be able to accurately switch a current of 16 mA @ 24 V.

1= black 2 = red3 = white 5 = orange 6 = pink7 = grey Signal assignement Modbus: C1 = D - = A

Cable colours:

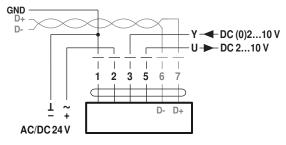
C2 = D + = B

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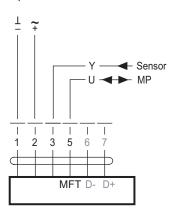


Electrical installation

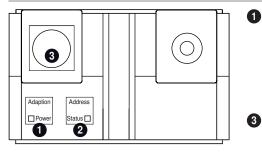
Modbus RTU / BACnet MS/TP with analog setpoint (hybrid mode)



Operation on the MP-Bus



Operating controls and indicators



1 Membrane key and LED display green

Membrane key ar	nd LED display green
Off:	No power supply or malfuntion
On:	In operation
Flashing:	In address mode: Pulses according to set address (116)
	When starting: Reset to factory setting (Communication)
Press button:	In standard mode: Triggers angle of rotation adaptation
	In address mode: Confirmation of set address (116)
Push-button and	LED display yellow
Off:	Standard mode
On:	Adaptation or synchronising process active
	or actuator in address mode (LED display green flashing)
Flickering:	BACnet / Modbus communication active
Press button:	In operation (>3 s): Switch address mode on and off
	In address mode: Address setting by pressing several times
	When starting (>5 s): Reset to factory setting (Communication)



For connecting parameterisation and service tools

Operating elements

The manual override, locking switch and direction of rotation switch elements are available on both sides

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Service			
Quick adressing	 Press the "Address" button until the green "Power" LED is no longer illuminated. LED flashes in accordance with the previously set address. Set the address by pressing the "Address" button the corresponding number of times (1-16). The green LED flashes in accordance with address that has been entered (1-16). If the address is not correct, then this can be reset in accordance with Step 2. Confirm the address setting by pressing the green "Adaption" button. If no confirmation occurs for 60 seconds, then the address procedure is ended. Any address change that has already been started will be discarded. The resulting BACnet MS/TP and Modbus RTU address is made up of the set basic address plus the short address (e.g. 100+7=107). 		
Service Tools connection	The actuator can be parameterised by ZTH EU via the s For an extended parameterisation the PC tool can be co $\frac{1}{-}$ + $\frac{AC}{DC} \frac{24 V}{24 V}$ $\frac{1}{-}$ + $\frac{1}{DC} \frac{24 V}{24 V}$ $\frac{1}{-}$ + $\frac{1}{-}$	onnected.	

Dimensions [mm]

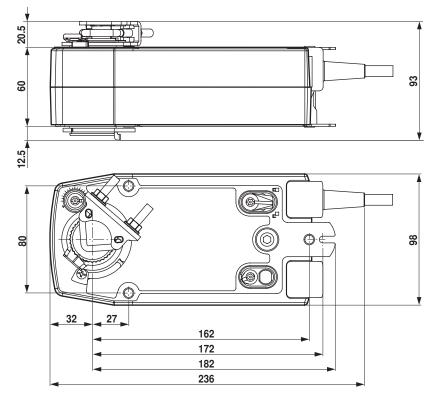
Spindle length

	Min. 85
	Min. 15

Clamping range

	<u>O</u> I	Ţ			
	1022	10		1425.4	
1					
	1925	5.4 1		1218	

Dimensional drawings



Further documentation

- Tool connections
- Description Protocol Implementation Conformance Statement PICS ٠
- Description Modbus register Overview MP Cooperation Partners •
- •
- ٠ MP Glossary
- Introduction to MP-Bus Technology ٠