

# **Technical data sheet**

MP/27BUS

Communicative rotary actuator failsafe for adjusting dampers in technical building installations

- Air damper size up to approx. 2 m<sup>2</sup>
- Torque motor 10 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Conversion of sensor signals
- Communication via Belimo MP-Bus



# **Technical data**

Electrical data	Nominal voltage	AC/DC 24 V				
	Nominal voltage frequency	50/60 Hz				
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V				
	Power consumption in operation	7 W				
	Power consumption in rest position	3.5 W				
	Power consumption for wire sizing	9.5 VA				
	Connection supply / control	Cable 1 m, 4 x 0.75 mm <sup>2</sup>				
	Parallel operation	Yes (note the performance data)				
Functional data	Torque motor	10 Nm				
	Torque fail-safe	10 Nm				
	Communicative control	MP-Bus				
	Operating range Y	210 V				
	Input Impedance	100 kΩ				
	Options positioning signal	Open/close				
		3-point (AC only)				
		Modulating (DC 032 V)				
	Operating range Y variable	Start point 0.530 V				
		End point 2.532 V				
	Position feedback U	210 V				
	Position feedback U note	Max. 0.5 mA				
	Position feedback U variable	Start point 0.58 V				
		End point 2.510 V				
	Position accuracy	±5%				
	Direction of motion motor	selectable with switch L/R				
	Direction of motion variable	electronically reversible				
	Direction of motion fail-safe	selectable by mounting L/R				
	Manual override	by means of hand crank and locking switch				
	Angle of rotation	Max. 95°				
	Angle of rotation note	adjustable starting at 33% in 2.5% steps (with mechanical end stop)				
	Running time motor	150 s / 90°				
	Running time motor variable	40150 s				
	Running time fail-safe	<20 s / 90°				
	Running time fail-safe note	@ -2050°C / <60 s @ -30°C				
	Adaptation setting range	manual				
	Adaptation setting range variable	No action				
		Adaptation when switched on				
	-	Adaptation after using the hand crank				
	Override control	MAX (maximum position) = 100%				
		MIN (minimum position) = $0\%$				
		ZS (intermediate position, AC only) = $50\%$				
	Override control variable	MAX = (MIN + 32%)100%				
		MIN = 0%(MAX – 32%) ZS = MINMAX				
	Sound power level, motor					
		40 dB(A)				
	Mechanical interface	Universal shaft clamp 1025.4 mm				
	Mechanical interface Position indication	Universal shaft clamp 1025.4 mm Mechanically, pluggable				
Safety	Mechanical interface	Universal shaft clamp 1025.4 mm				



Safety						
	Protection class UL	UL Class 2 Supply				
	Degree of protection IEC/EN	IP54				
	Degree of protection NEMA/UL	NEMA 2				
	Enclosure EMC	UL Enclosure Type 2 CE according to 2014/30/EU				
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14				
	Certification UL	cULus according to UL60730-1A, UL60730-2- 14 and CAN/CSA E60730-1:02				
	Certification UL note	The UL marking on the actuator depends on the production site, the device is UL-compliant in				
	Mode of operation	any case Type 1.AA				
	Rated impulse voltage supply / control	0.8 kV				
	Control pollution degree	3				
	Ambient temperature	-3050°C				
	Storage temperature	-4080°C				
	Ambient humidity	Max. 95% r.H., non-condensing				
	Servicing	maintenance-free				
Weight	Weight	2.0 kg				
Safety notes						
$\bigwedge$	The device must not be used outside in aircraft or in any other airborne me	the specified field of application, especially ne				
	• Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.					
	<ul> <li>Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.</li> </ul>					
	<ul> <li>The device may only be opened at the manufacturer's site. It does not contain a parts that can be replaced or repaired by the user.</li> <li>The device contains electrical and electronic components and must not be disp of as household refuse. All locally valid regulations and requirements must be observed.</li> <li>Cables must not be removed from the device.</li> </ul>					
Product features						
Product features Mode of operation	to the position defined by the positionin electrical display of the damper positio other actuators. Operation on Bus: The actuator receives its digital positio the MP-Bus and drives to the position					
	The actuator is connected with a stand to the position defined by the positionin electrical display of the damper positio other actuators. Operation on Bus: The actuator receives its digital position the MP-Bus and drives to the position interface and does not supply an analoc Connection option for a sensor (passiv	ng signal. Measuring voltage U serves for the n 0.5100% and as slave control signal for hing signal from the higher level controller via defined. Connection U serves as communication gue measuring voltage. e or active sensor or switching contact). The gital converter for the transmission of the sensor				
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Mode of operation Converter for sensors Parametrisable actuators	The actuator is connected with a stand to the position defined by the positionin electrical display of the damper positio other actuators. Operation on Bus: The actuator receives its digital positio the MP-Bus and drives to the position interface and does not supply an analo Connection option for a sensor (passiv MP actuator serves as an analogue/dig signal via MP-Bus to the higher level s The factory settings cover the most con modified with the Belimo Service Tools Simple direct mounting on the damper an anti-rotation device to prevent the a By using the hand crank the damper ca	ng signal. Measuring voltage U serves for the n 0.5100% and as slave control signal for hing signal from the higher level controller via defined. Connection U serves as communication gue measuring voltage. e or active sensor or switching contact). The gital converter for the transmission of the sense ystem. mmon applications. Single parameters can be MFT-P or ZTH EU. shaft with a universal shaft clamp, supplied with				

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Product features			
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.		
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position $(0\%)$ . The actuator then moves into the position defined by the positioning signal.		
Adaption and synchronisation	An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after actuating the hand crank is programmed. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)		

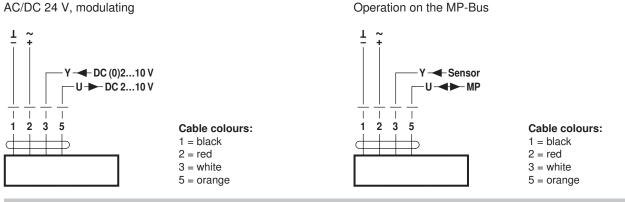
# Accessories

	Description	Туре
Gateways	Gateway MP zu BACnet MS/TP	UK24BAC
	Gateway MP to Modbus RTU	UK24MOD
	Gateway MP to LonWorks	UK24LON
	Gateway MP to KNX	UK24EIB
	Description	Туре
Electrical accessories	Auxiliary switch 2 x SPDT	S2A-F
	Feedback potentiometer 200 Ω	P200A-F
	Feedback potentiometer 1 kΩ	P1000A-F
	Signal converter voltage/current 100 kΩ Supply AC/DC 24 V	Z-UIC
	Range controller for wall mounting	SBG24
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	CRP24-B1
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin service socket for Belimo device	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	Connecting board MP-Bus for wiring boxes EXT-WR-FPMP	ZFP2-MP
	MP-Bus power supply for MP actuators	ZN230-24MP
	Description	Туре
Mechanical accessories	Shaft extension 240 mm Ø20 mm for damper shaft Ø 822.7 mm	AV8-25
	End stop indicator	IND-AFB
	Shaft clamp reversible, for central mounting, for damper shafts Ø12.7 / 19.0 / 25.4 mm	K7-2
	Ball joint suitable for damper crank arm KH8 / KH10	KG10A
	Ball joint suitable for damper crank arm KH8	KG8
	Damper crank arm Slot width 8.2 mm, clamping range Ø1018 mm	KH8
	Actuator arm, for 3/4" shafts, clamping range Ø1022 mm, Slot width 8.2 mm	KH-AFB
	Form fit insert 10x10 mm, Multipack 20 pcs.	ZF10-NSA-F
	Form fit insert 12x12 mm, Multipack 20 pcs.	ZF12-NSA-F
	Form fit insert 15x15 mm, Multipack 20 pcs.	ZF15-NSA-F
	Form fit insert 16x16 mm, Multipack 20 pcs.	ZF16-NSA-F
	Mounting kit for linkage operation for flat and side installation	ZG-AFB
	Base plate extension	Z-SF
	Anti-rotation mechanism 230 mm, Multipack 20 pcs.	Z-ARS230L
	Actuator arm, for 3/4" shafts, clamping range Ø1022 mm, Slot width 8.2 mm Form fit insert 10x10 mm, Multipack 20 pcs. Form fit insert 12x12 mm, Multipack 20 pcs. Form fit insert 15x15 mm, Multipack 20 pcs. Form fit insert 16x16 mm, Multipack 20 pcs. Mounting kit for linkage operation for flat and side installation	KH-AFB ZF10-NSA-F ZF12-NSA-F ZF15-NSA-F ZF16-NSA-F ZG-AFB Z-SF



		Description	Туре
	Service Tools	Service Tool, with ZIP-USB function	ZTH EU
		Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
		Adapter for Service-Tool ZTH	MFT-C
Electrical installation			
$\Lambda$	Notes	<ul> <li>Connection via safety isolating transformer.</li> <li>Parallel connection of other actuators possible. Observe the second seco</li></ul>	ne performance da

### Wiring diagrams



A) more actuators and sensors

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• Supply AC/DC 24 V

(max. DC 0...32 V)

Resolution 30 mV

• Output signal DC 0...10 V

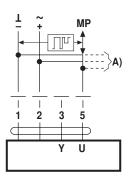
(max.8)

(max.8)

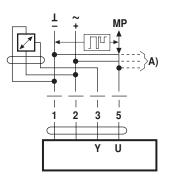
### **Functions**

### Functions when operated on MP-Bus

Connection on the MP-Bus



Connection of active sensors



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Connection of external switching contact

A) more actuators and sensors (max.8)

• Switching current 16 mA @ 24 V • Start point of the operating range must be parameterised on the MP actuator as  $\geq 0.5$  V

MP-Bus Network topology

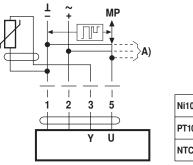
There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable • no shielding or twisting necessary

no terminating resistors required



# Functions

Connection of passive sensors

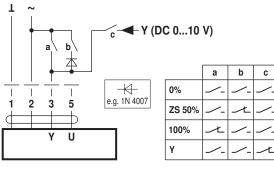


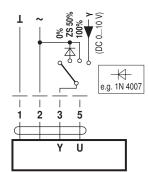
Ni1000	–28+98°C	8501600 Ω <sup>2)</sup>
PT1000	–35+155°C	8501600 Ω <sup>2)</sup>
NTC	-10+160°C <sup>1)</sup>	200 Ω60 kΩ <sup>2)</sup>

A) more actuators and sensors (max.8)1) Depending on the type2) Resolution 1 Ohm

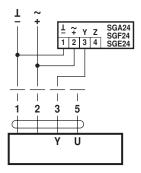
### Functions with basic values (conventional mode)

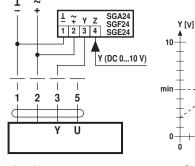
Override control with AC 24 V with relay contacts



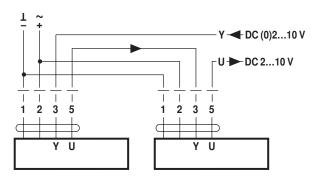


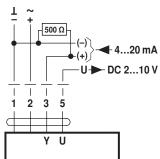
Control remotely 0...100% with Minimum limit with positioner SG..



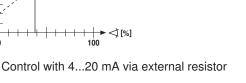


Follow-up control (position-dependent)





Override control with AC 24 V with rotary switch



Caution:

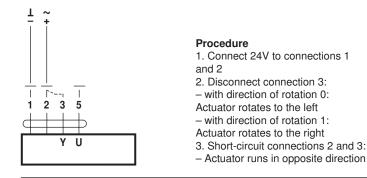
The operating range must be set to DC 2...10 V. The 500  $\Omega$  resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

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## **Functions**

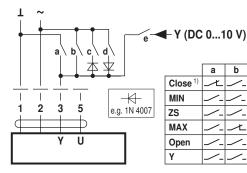
### Functional check



### Functions for devices with specific parameters (Parametrisation necessary)

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Override control and limiting with AC 24 V with relay contacts



Control 3-point

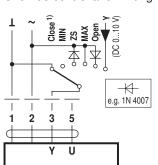
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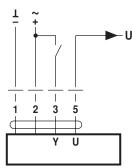
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(C)

Triggers angle of rotation adaptation, followed by standard mode

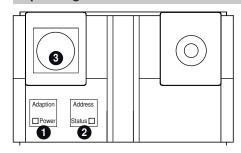
Override control and limiting with AC 24 V with rotary switch

1) Caution: This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.



Control open/close

# **Operating controls and indicators**



0	Membrane	key	and	LED	display	green
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No power supply or malfuntion

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e.g. 1N 4007

Off: On:

Press button:

### 2 Membrane key and LED display gelb

Off: Standard mode MP communication active Flickering: Adaptation and synchronising process active On: Flashing: Request for addressing from MP master Press button: Confirmation of the addressing

### 3 Service plug

For connecting parameterisation and service tools

In operation

### **Operating elements**

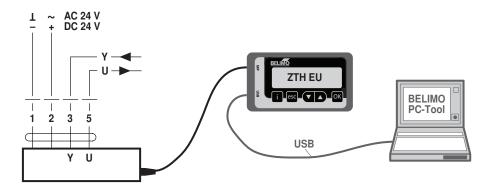
The manual override, locking switch and direction of rotation switch elements are available on both sidesa



## Service

Service Tools connection

tion The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected. Connection ZTH EU / PC-Tool



## **Dimensions** [mm]

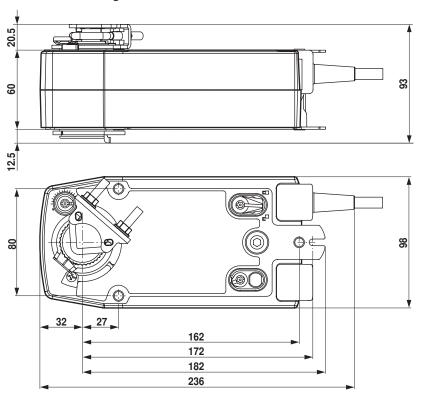
### Spindle length



### **Clamping range**

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	1022	10		1425.4
1	<u> </u>			
	1925	5.4 1		218

### **Dimensional drawings**



### **Further documentation**

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology