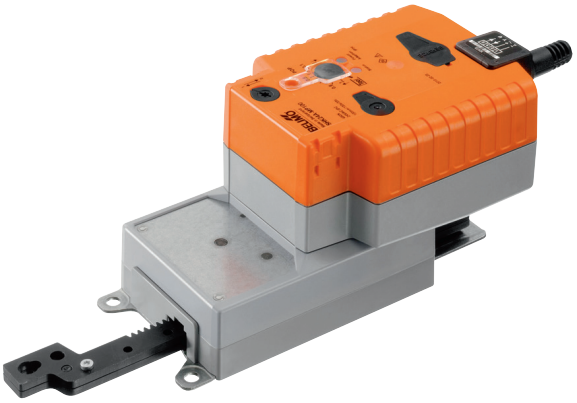
Technical data sheet LHK24A-MP100

Communicative linear actuator fail-safe and extended functionalities for adjusting dampers and slide valves in technical building installations and in laboratories

- **Air damper size up to approx. 1 m²**
- **Actuating force 150 N**
- **Nominal voltage AC/DC 24 V**
- **Control modulating, communicative 2...10 V variable**
- **Position feedback 2...10 V variable**
- **Length of Stroke Max. 100 mm, adjustable in 20 mm increments**
- **Conversion of sensor signals**
- **Communication via Belimo MP-Bus**



MP-BUS

Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	7 W
	Power consumption in rest position	3 W
	Power consumption for wire sizing	14 VA
	Power consumption for wire sizing note	Imax 20 A @ 5 ms
	Connection supply / control	Cable 1 m, 4 x 0.75 mm²
	Parallel operation	Yes (note the performance data)
Functional data	Actuating force motor	150 N
	Communicative control	MP-Bus
	Operating range Y	2...10 V
	Input Impedance	100 kΩ
	Options positioning signal	Open/close 3-point (AC only) Modulating (DC 0...32 V)
	Operating range Y variable	Start point 0.5...30 V End point 2.5...32 V
	Position feedback U	2...10 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point 0.5...8 V End point 2.5...10 V
	Setting fail-safe position	0...100%, adjustable in increments of 10% (POP rotary knob on 0 corresponds to retracted gear rod)
	Bridging time (PF)	2 s
	Bridging time (PF) variable	0...10 s
	Position accuracy	±5%
	Direction of motion motor	selectable with switch
	Direction of motion note	Y = 0 V: with switch 0 (retracted) / 1 (extended)
	Direction of motion variable	electronically reversible
	Direction of motion fail-safe	selectable with switch 0...100% (retracted 0%)
	Manual override	with push-button
	Stroke	100 mm
	Length of Stroke	Max. 100 mm, adjustable in 20 mm increments
	Stroke limitation	can be limited on both sides with mechanical end stops
	Running time motor	120 s / 100 mm
	Running time motor variable	60...120 s / 100 mm
	Running time fail-safe	35 s / 100 mm
	Running time fail-safe note	<35 s @ 0...50°C
	Adaptation setting range	manual
	Adaptation setting range variable	No action Adaptation when switched on Adaptation after pushing the gear disengagement button
	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%

Technical data

Functional data	Override control variable	MAX = (MIN + 5%)...100% MIN = 0%...(MAX – 5%) ZS = MIN...MAX
	Sound power level, motor	52 dB(A)
	Sound power level, fail-safe	65 dB(A)
Safety	Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)
	Protection class UL	UL Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Certification UL	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1:02
	Certification UL note	The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
	Mode of operation	Type 1.AA
	Rated impulse voltage supply / control	0.8 kV
	Control pollution degree	3
	Ambient temperature	-30...50°C
	Storage temperature	-40...80°C
	Ambient humidity	Max. 95% r.H., non-condensing
	Servicing	maintenance-free
Weight	Weight	1.0 kg
Terms	Abbreviations	POP = Power off position / fail-safe position PF = Power fail delay time / bridging time

Safety notes

- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The rotary supports and coupling pieces available as accessories and must always be used if transverse forces are likely. In addition, the actuator must not be tightly bolted to the application. It must remain movable via the rotary support (refer to «Assembly notes»).
- If a rotary support and/or coupling piece is used, actuation force losses are to be expected.
- If the actuator is exposed to severely contaminated ambient air, appropriate precautions must be taken on the system side. Excessive deposits of dust, soot etc. can prevent the gear rod from being extended and retracted correctly.
- If not installed horizontally, the gear disengagement push-button may only be actuated when there is no pressure on the gear rod.
- To calculate the actuating force required for air dampers and slide valves, the specifications supplied by the damper manufacturers concerning the cross section, the design, the installation site and the ventilation conditions must be observed.
- Self-adaptation is necessary when the system is commissioned or whenever the stroke limiting is adjusted (press the adaptation push-button).
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

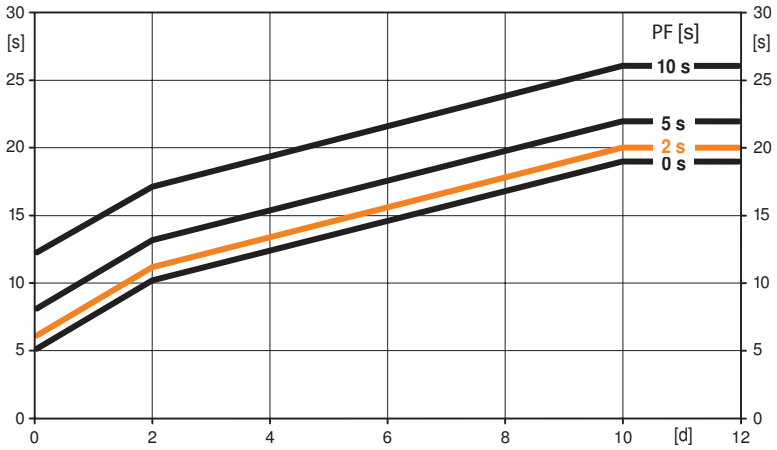
The actuator moves the damper to the desired operating position at the same time as the integrated capacitors are charged. Interrupting the supply voltage causes the damper to be rotated back into the fail-safe position by means of stored electrical energy.
Conventional operation:
The actuator is connected with a standard modulating signal of 0...10 V and drives to the position defined by the positioning signal. Measuring voltage U serves for the electrical display of the damper position 0.5...100% and as a slave control signal for other actuators.
Operation on Bus:
The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Product features

Pre-charging time (start up)

The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset fail-safe position.
The duration of the pre-charging time depends mainly on following factors:
– Duration of the power failure
– PF delay time (bridging time)

Typical pre-charging time



PF [s]	[d]				
	0	**1**	**2**	**7**	**≥10**
0	5	8	10	15	19
2	6	9	11	16	20
5	8	11	13	18	22
10	12	15	17	22	26
	[s]				

[d] = Electricity interruption in days
[s] = Pre-charging time in seconds
PF[s] = Bridging time
Calculation example: Given an electricity interruption of 3 days and a bridging time (PF) set at 5 s, the actuator requires a pre-charging time of 14 s after the electricity has been reconnected (see graphic).

Delivery condition (capacitors)

The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 20 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parametrisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

Simple direct mounting

The actuator can be directly connected with the application using the enclosed screws. The head of the gear rod is connected to the moving part of the ventilating application individually on the mounting side or with the Z-KS2 coupling piece provided.

Manual override

Manual control with push-button possible - temporary. The gear is disengaged and the actuator decoupled for as long as the button is pressed.

Adjustable stroke

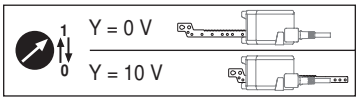
If a stroke limitation will be adjusted, the mechanical operating range on this side of the gear rod can be used starting with an extension length of 20 mm and then can be limited respectively in increments of 20 mm by means of mechanical end stops Z-AS2.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).
The actuator then moves into the position defined by the positioning signal.



Product features

Setting direction of stroke

When actuated, the stroke direction switch changes the running direction in normal operation. The stroke direction switch has no influence on the fail-safe position which has been set.

Setting fail-safe position (POP)

The rotary knob fail-safe position can be used to adjust the desired fail-safe position 0...100% in 10% increments. The rotary knob only refers to the adapted stroke range 30...100mm. No set min or max values are observed. In the event of a power failure, the actuator will move into the selected fail-safe position, taking into account the bridging time which was set.
Settings: The rotary knob must be set to the «Tool» position for retroactive settings of the fail-safe position with the Belimo service tool MFT-P. Once the rotary knob is set back to the range 0…100%, the manually set value will have positioning authority.

Bridging time

Electrical interruptions can be bridged up to a maximum of 10 s.
In the event of a power failure, the actuator will remain stationary in accordance with the set bridging time. If the power failure is greater than the set bridging time, then the actuator will move into the selected fail-safe position.
The bridging time set ex-works is 2 s. This can be modified on site in operation with the use of the Belimo service tool MFT-P.
Settings: The rotary knob must not be set to the “Tool” position!
For retroactive adjustments of the bridging time with the Belimo service tool MFT-P or with the ZTH EU adjustment and diagnostic device only the values need to be entered.

Adaption and synchronisation

An adaption can be triggered manually by pressing the “Adaption” button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).
A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

Accessories

	Description	Type
Gateways	Gateway MP to Modbus RTU	UK24MOD
	Gateway MP zu BACnet MS/TP	UK24BAC
	Gateway MP to LonWorks	UK24LON
	Gateway MP to KNX	UK24EIB

	Description	Type
Electrical accessories	Signal converter voltage/current 100 kΩ Supply AC/DC 24 V	Z-UIC
	Range controller for wall mounting	SBG24
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	CRP24-B1
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin service socket for Belimo device	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	Connecting board MP-Bus for wiring boxes EXT-WR-FP..-MP	ZFP2-MP
	MP-Bus power supply for MP actuators	ZN230-24MP

	Description	Type
Mechanical accessories	End stop kit, Multipack 20 pcs.	Z-AS2
	Rotary support, for linear actuator	Z-DS1
	Coupling piece M6	Z-KS2

	Description	Type
Service Tools	Service Tool, with ZIP-USB function	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH	MFT-C

Electrical installation

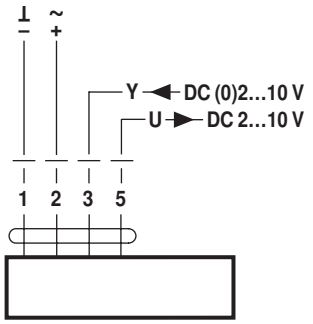
Electrical installation

Notes

- Connection via safety isolating transformer.
- Parallel connection of other actuators possible. Observe the performance data.

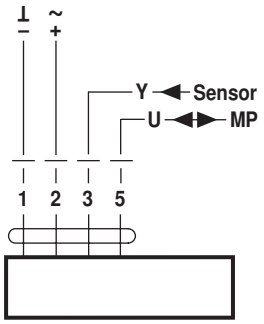
Wiring diagrams

AC/DC 24 V, modulating



Cable colours:
1 = black
2 = red
3 = white
5 = orange

Operation on the MP-Bus



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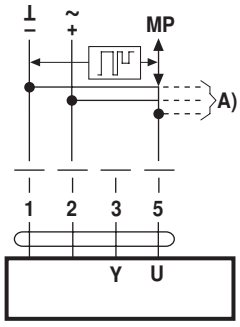
Functions

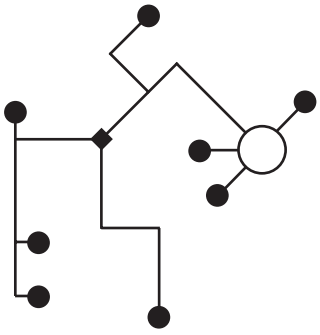
Functions when operated on MP-Bus

Connection on the MP-Bus



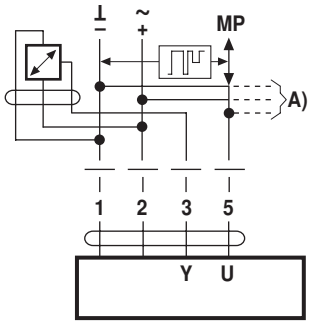
A) more actuators and sensors (max.8)

MP-Bus Network topology



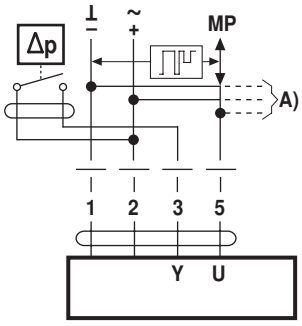
There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).
Supply and communication in one and the same 3-wire cable
- no shielding or twisting necessary
- no terminating resistors required

Connection of active sensors



A) more actuators and sensors (max.8)
- Supply AC/DC 24 V
- Output signal DC 0...10 V (max. DC 0...32 V)
- Resolution 30 mV

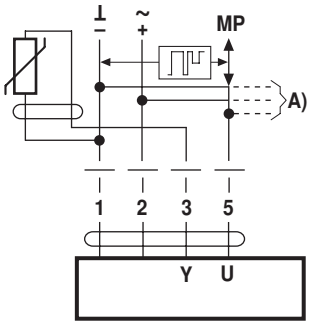
Connection of external switching contact



A) more actuators and sensors (max.8)
- Switching current 16 mA @ 24 V
- Start point of the operating range must be parameterised on the MP actuator as ≥ 0.5 V

Functions

Connection of passive sensors

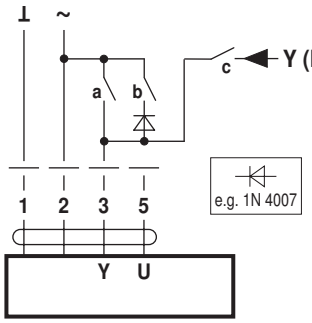


Ni1000	–28...+98 °C	850...1600 Ω 2)
PT1000	–35...+155 °C	850...1600 Ω 2)
NTC	–10...+160 °C 1)	200 Ω...60 kΩ 2)

A) more actuators and sensors (max.8)
1) Depending on the type
2) Resolution 1 Ohm

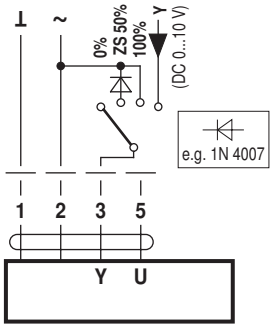
Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts

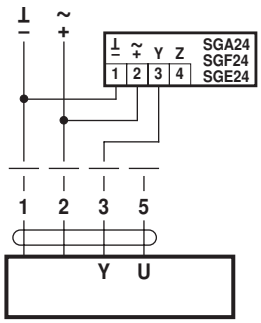


	a	b	c
0%	_	_	_
ZS 50%	_	⌐	_
100%	⌐	_	_
Y	_	_	⌐

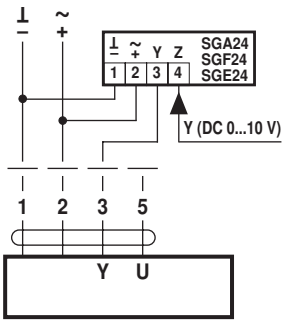
Override control with AC 24 V with rotary switch

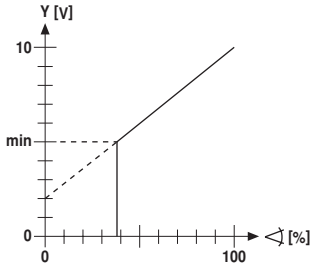


Control remotely 0...100% with positioner SG..

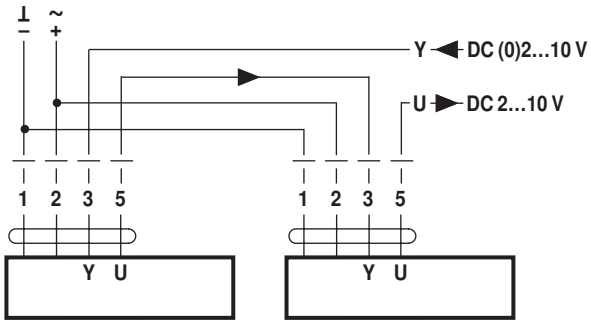


Minimum limit with positioner SG..

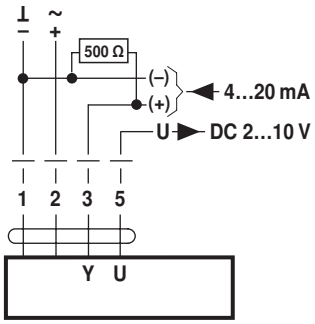




Follow-up control (position-dependent)



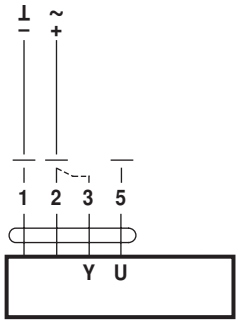
Control with 4...20 mA via external resistor



Caution:
The operating range must be set to DC 2...10 V.
The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

Functions

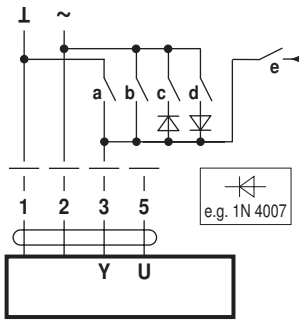
Functional check



Procedure
1. Apply 24 V to connection 1 and 2
2. Disconnect connection 3:
- for direction of stroke 0: Actuator travels in the direction “retracted”
- for direction of stroke 1: Actuator travels in the direction “extended”
3. Short circuit connections 2 and 3:
- Actuator runs in the opposite direction

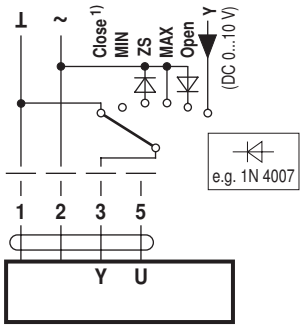
Functions for devices with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts



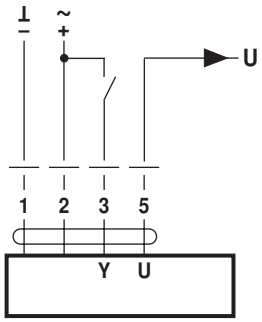
	a	b	c	d	e
Close [1]	⌐	_	_	_	_
MIN	_	⌐	_	_	_
ZS	_	_	⌐	_	_
MAX	_	⌐	_	_	_
Open	_	_	_	⌐	_
Y	_	_	_	_	⌐

Override control and limiting with AC 24 V with rotary switch

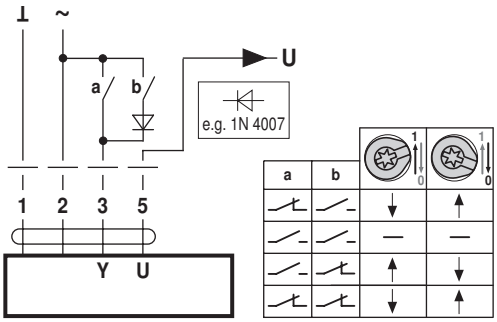


1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

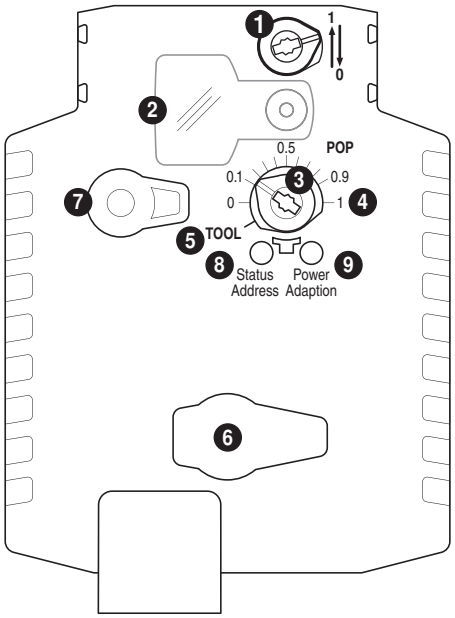
Control open/close



Control 3-point



Operating controls and indicators

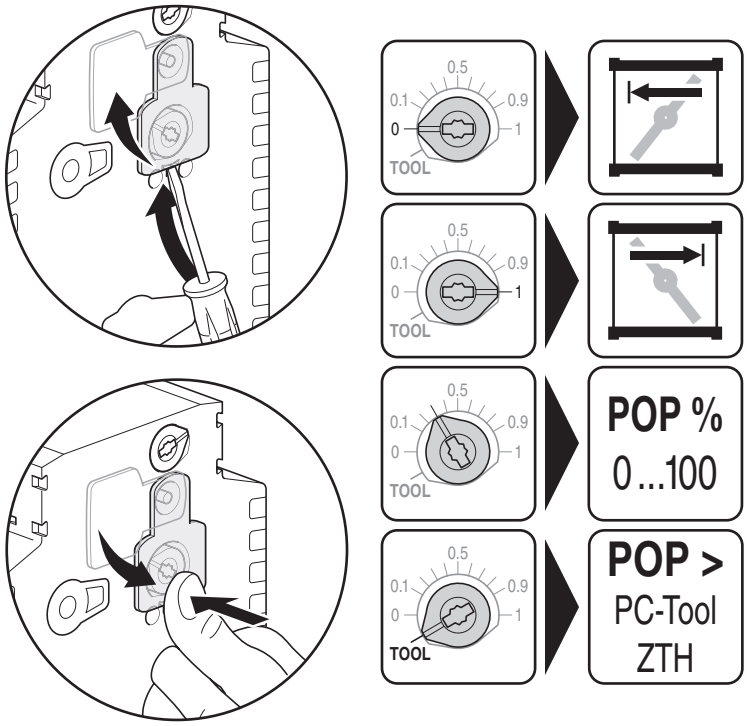


1. **Direction of stroke switch**
2. **Cover, POP button**
3. **POP button**
4. **Scale for manual adjustment**
5. **Position for adjustment with tool**
6. **Tool socket**
7. **Disengagement button**

LED displays 8 yellow	LED displays 9 green	Meaning / function
Off	On	Operation OK / without fault
Off	Flashing	POP function active
On	Off	Fault
Off	Off	Not in operation
On	On	Adaptation procedure running
Flashing	On	Communication

8. **Press button:** Acknowledgment of addressing
9. **Press button:** Triggers stroke adaption, followed by standard operation

Setting emergency setting position (POP)



Installation notes

Notes

- If a rotary support and/or coupling piece is used, losses in the actuation force losses are to be expected.

Applications without transverse force

The linear actuator is screwed directly to the housing at three points. Afterwards, the head of the gear rod is fastened to the moving part of the ventilation application (e.g. damper or slide valve).

Applications with transverse forces

Connect the coupling piece with the internal thread (Z-KS2) to the head of the gear rod. Screw the rotary support (Z-DS1) to the ventilation application. Afterwards, the linear actuator is screwed to the previously mounted rotary support with the enclosed screw. Then, the coupling piece, which is mounted to the head of the gear rod, is attached to the moving part of the ventilating application (e.g. damper or slide valve). The transverse forces can be compensated for to a certain limit with the rotary support and/or coupling piece. The maximum permissible swivel angle of the rotary support and coupling piece is 10°, laterally and upwards.

Stroke limitation

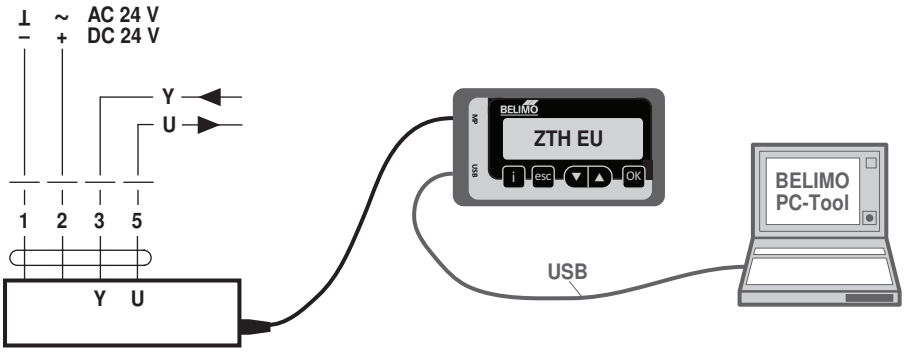
If the stroke limitations are used on the gear rod, the mechanical operating range on this side of the gear rod can be used starting with an extension length of 20 mm.

Service

Service Tools connection

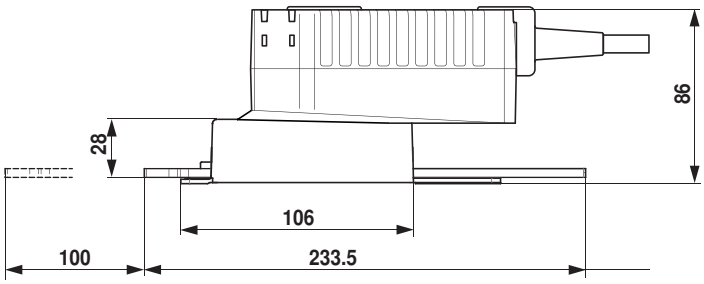
The actuator can be parametrised by ZTH EU via the service socket.
For an extended parametrisation the PC tool can be connected.

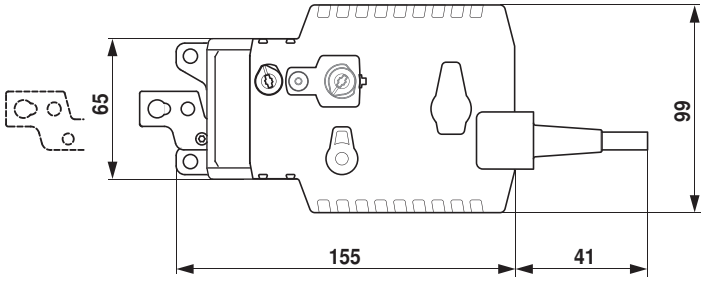
Connection ZTH EU / PC-Tool



Dimensions [mm]

Dimensional drawings





Further documentation

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology